



Falling In Love Rose

Rosa 'WEKmoomar'

Height: 4 feet

Spread: 4 feet

Sunlight: ☉

Hardiness Zone: 6a

Group/Class: Hybrid Tea Rose

Description:

This variety produces large, classically shaped, soft pink blooms; a prolific early summer bloomer that will continue until fall on sturdy, bushy plants; good disease resistance

Ornamental Features

Falling In Love Rose features showy fragrant shell pink flowers at the ends of the branches from early summer to early fall. The flowers are excellent for cutting. It has dark green foliage throughout the season. The glossy oval compound leaves turn yellow in fall. The fruit is not ornamentally significant.

Landscape Attributes

Falling In Love Rose is a multi-stemmed deciduous shrub with an upright spreading habit of growth. Its average texture blends into the landscape, but can be balanced by one or two finer or coarser trees or shrubs for an effective composition.

This shrub will require occasional maintenance and upkeep, and is best pruned in late winter once the threat of extreme cold has passed. Gardeners should be aware of the following characteristic(s) that may warrant special consideration;

- Spiny

Falling In Love Rose is recommended for the following landscape applications;

- Accent
- Mass Planting
- Hedges/Screening
- General Garden Use



Falling In Love Rose flowers
Photo courtesy of NetPS Plant Finder



Planting & Growing

Falling In Love Rose will grow to be about 4 feet tall at maturity, with a spread of 4 feet. It tends to fill out right to the ground and therefore doesn't necessarily require facer plants in front. It grows at a fast rate, and under ideal conditions can be expected to live for approximately 20 years.

This shrub should only be grown in full sunlight. It does best in average to evenly moist conditions, but will not tolerate standing water. It is not particular as to soil type or pH. It is highly tolerant of urban pollution and will even thrive in inner city environments. This particular variety is an interspecific hybrid.